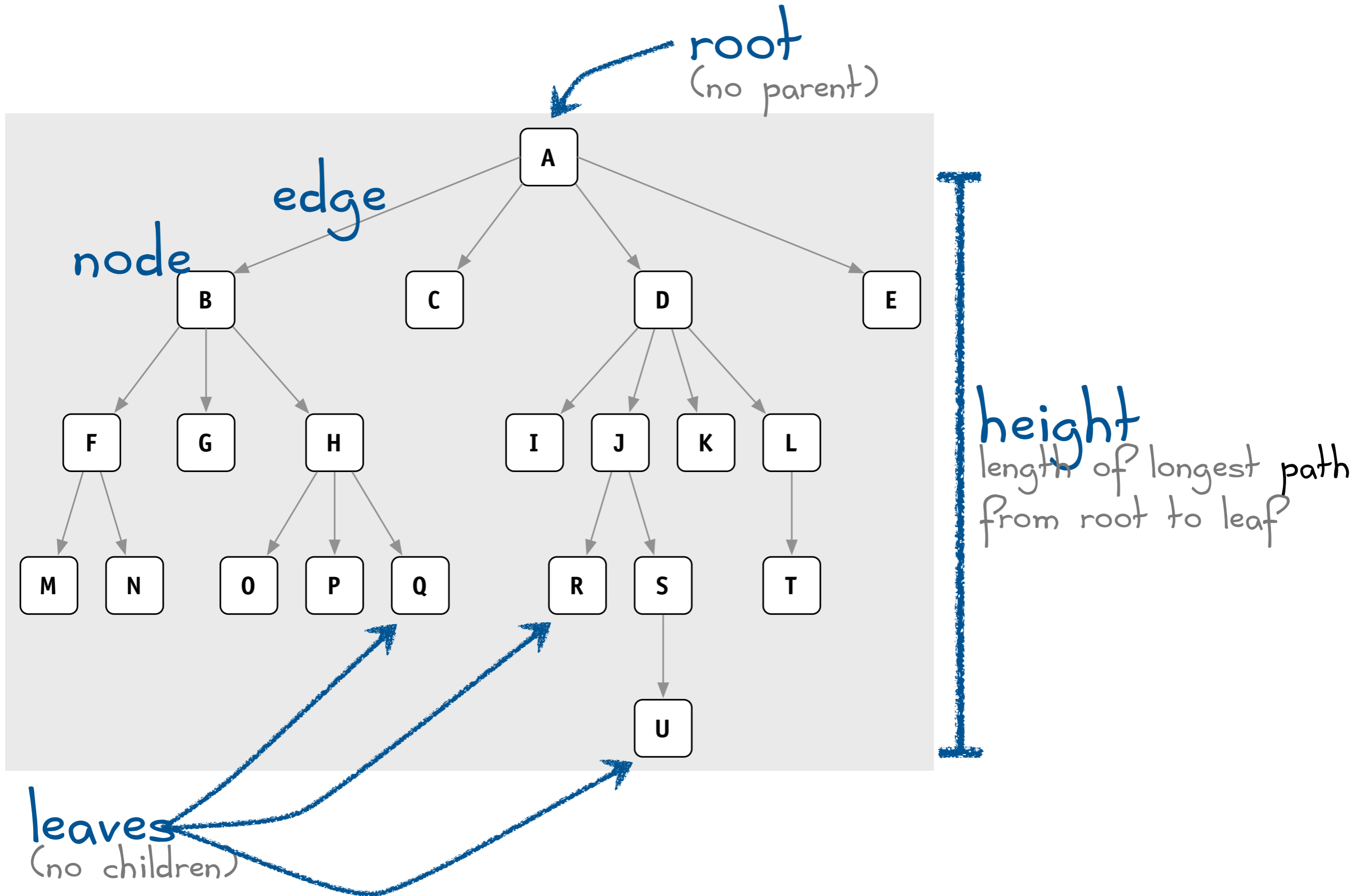


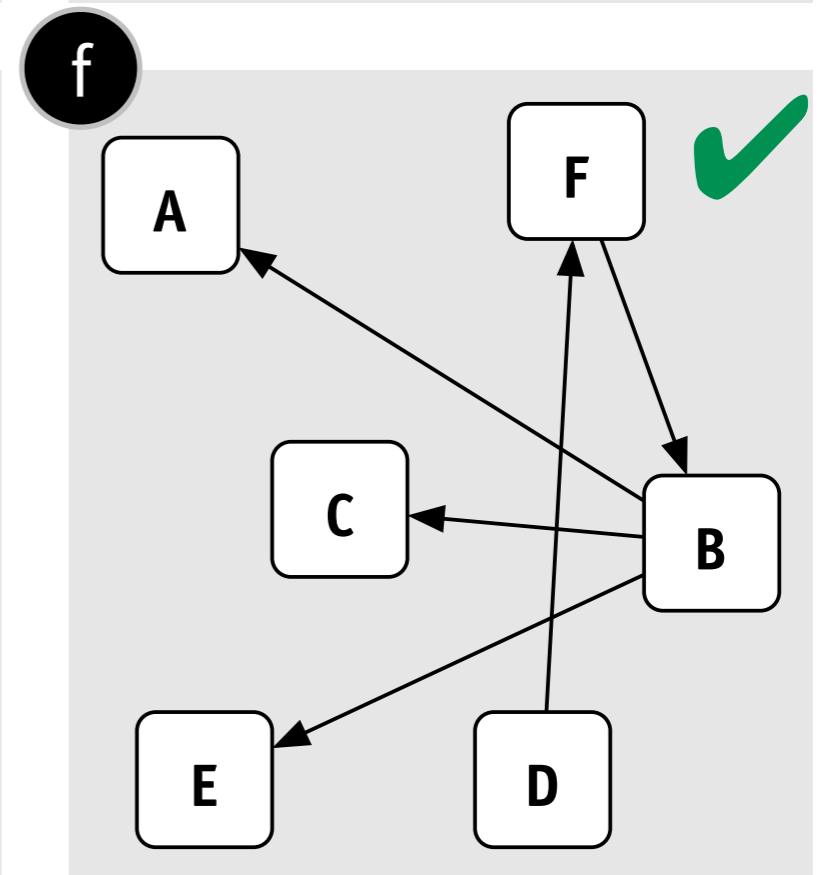
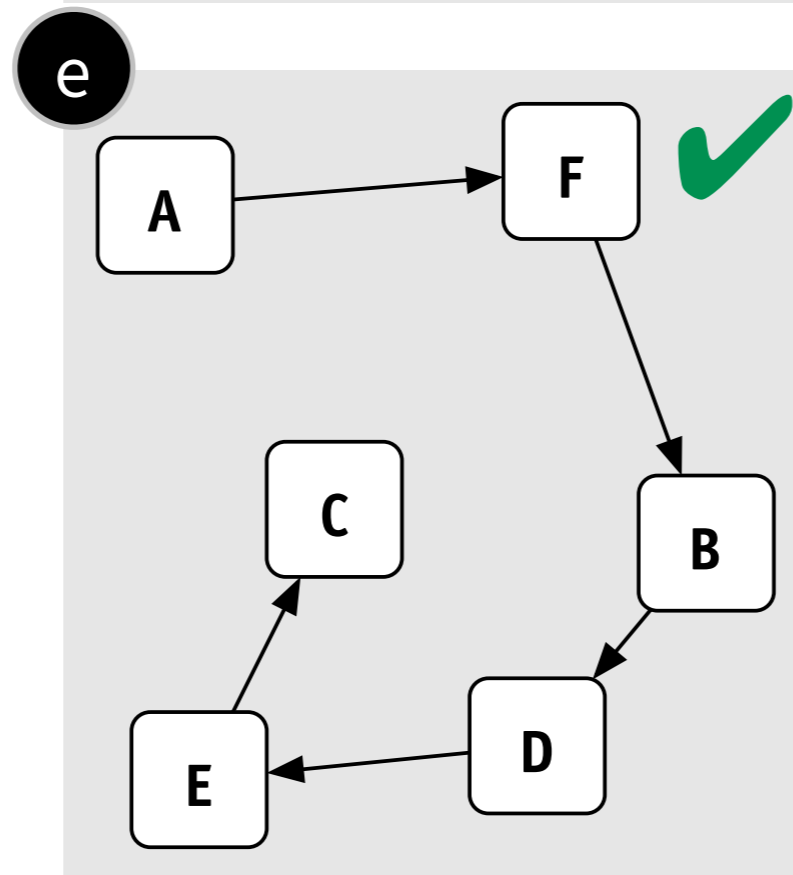
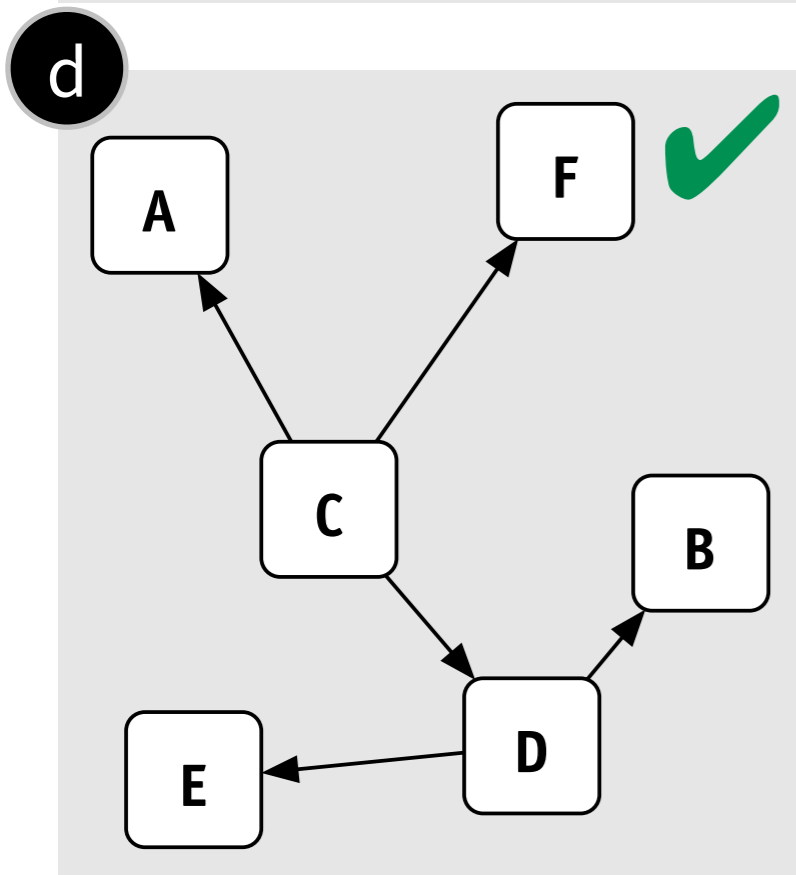
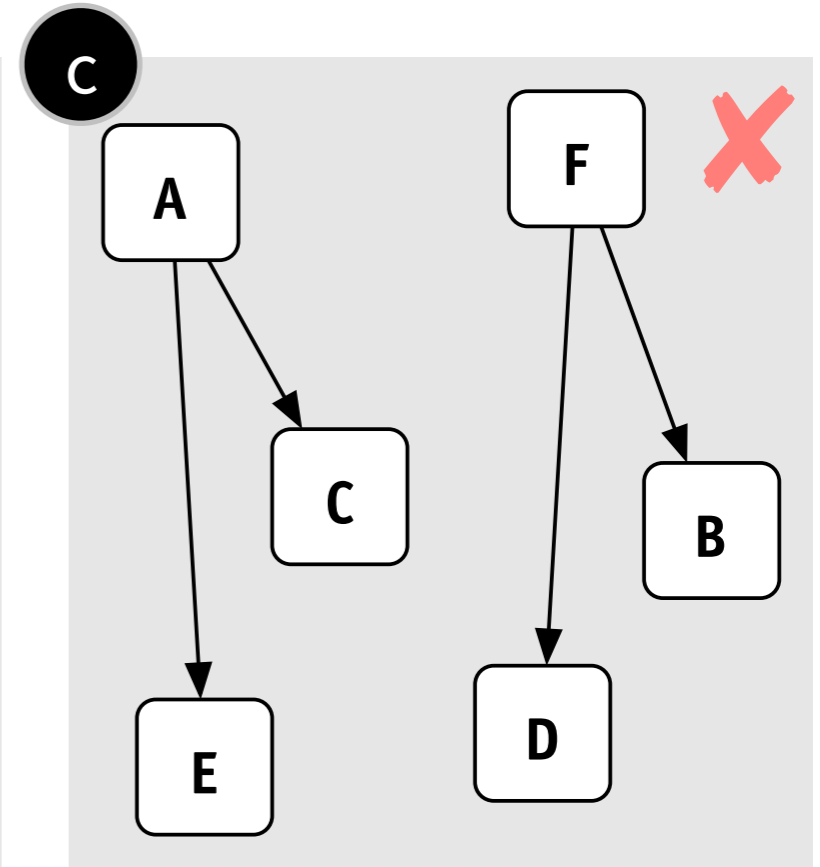
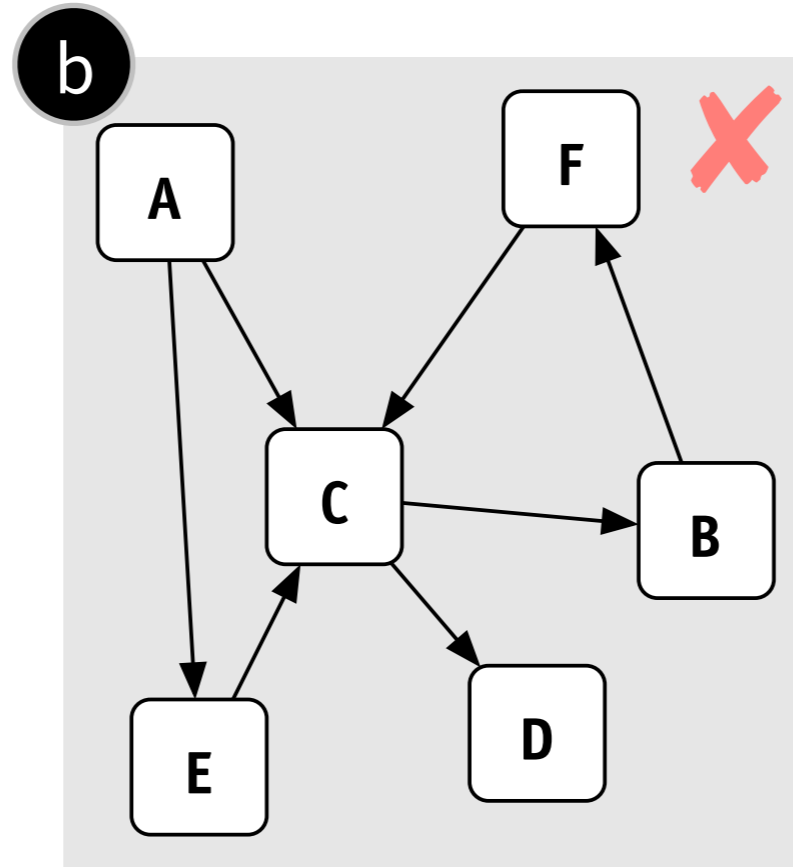
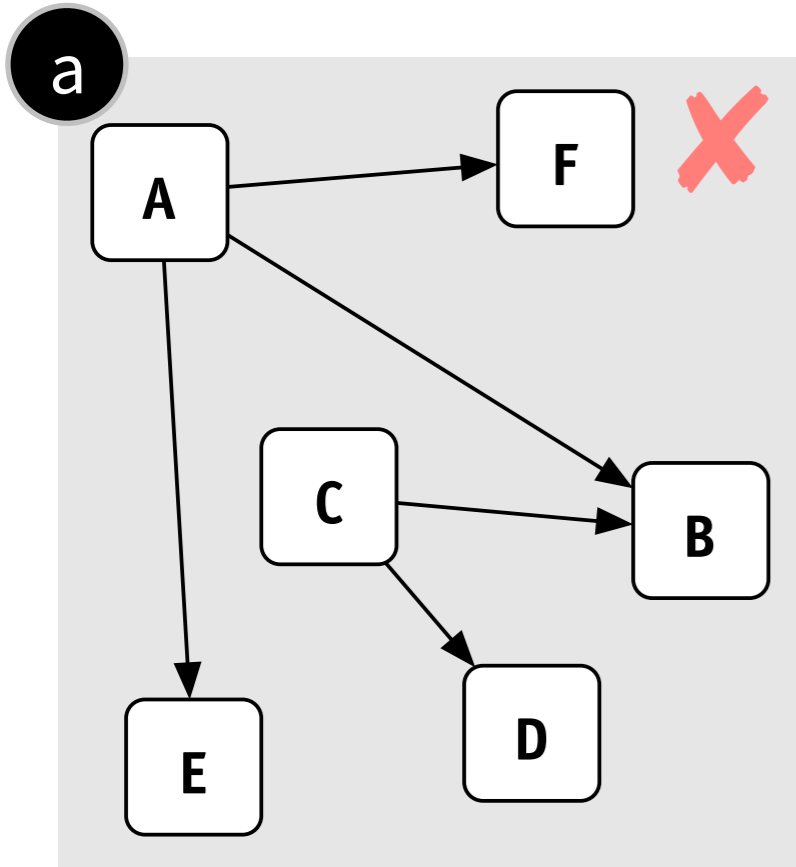


Trees

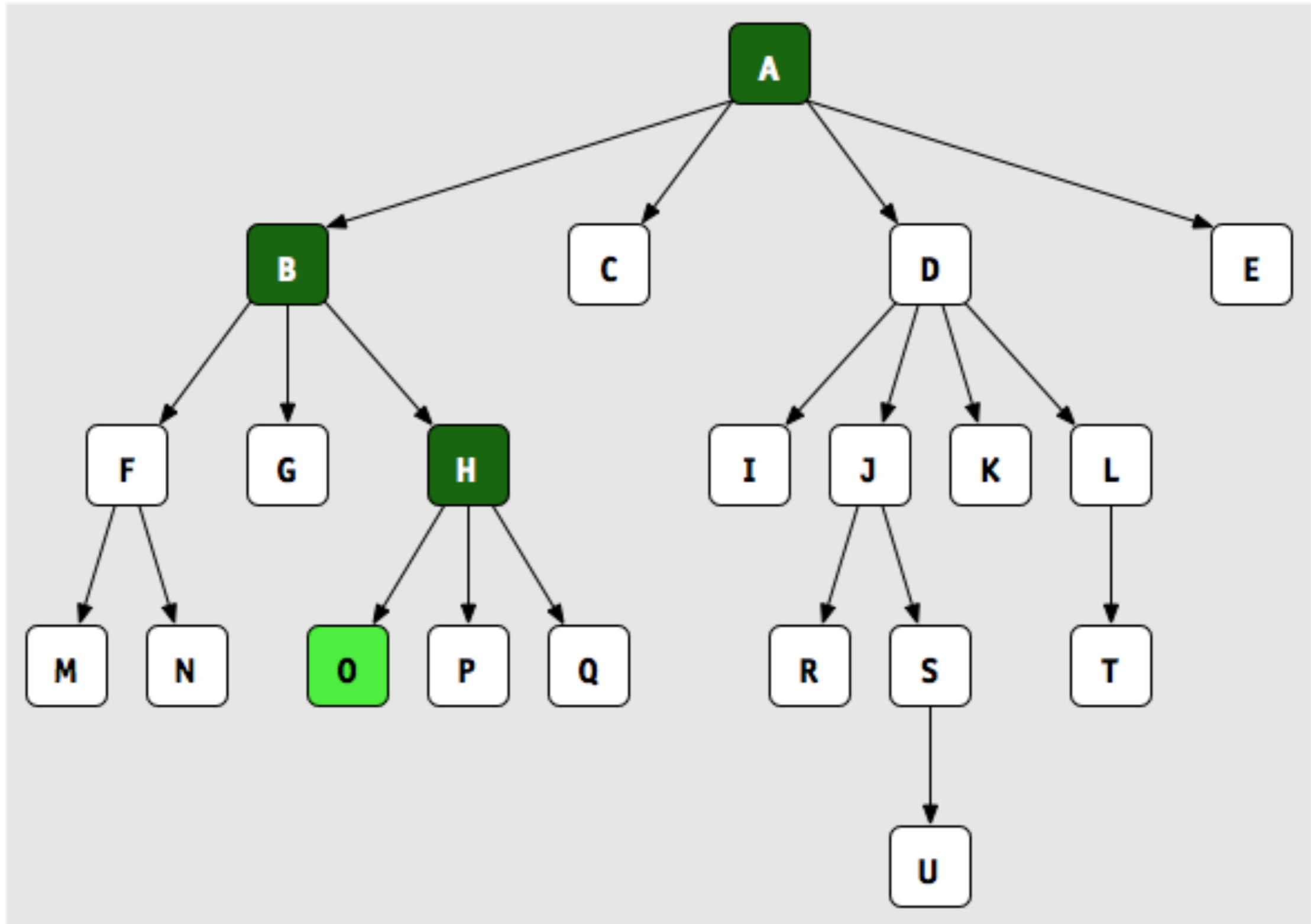
a unique path from root to every element



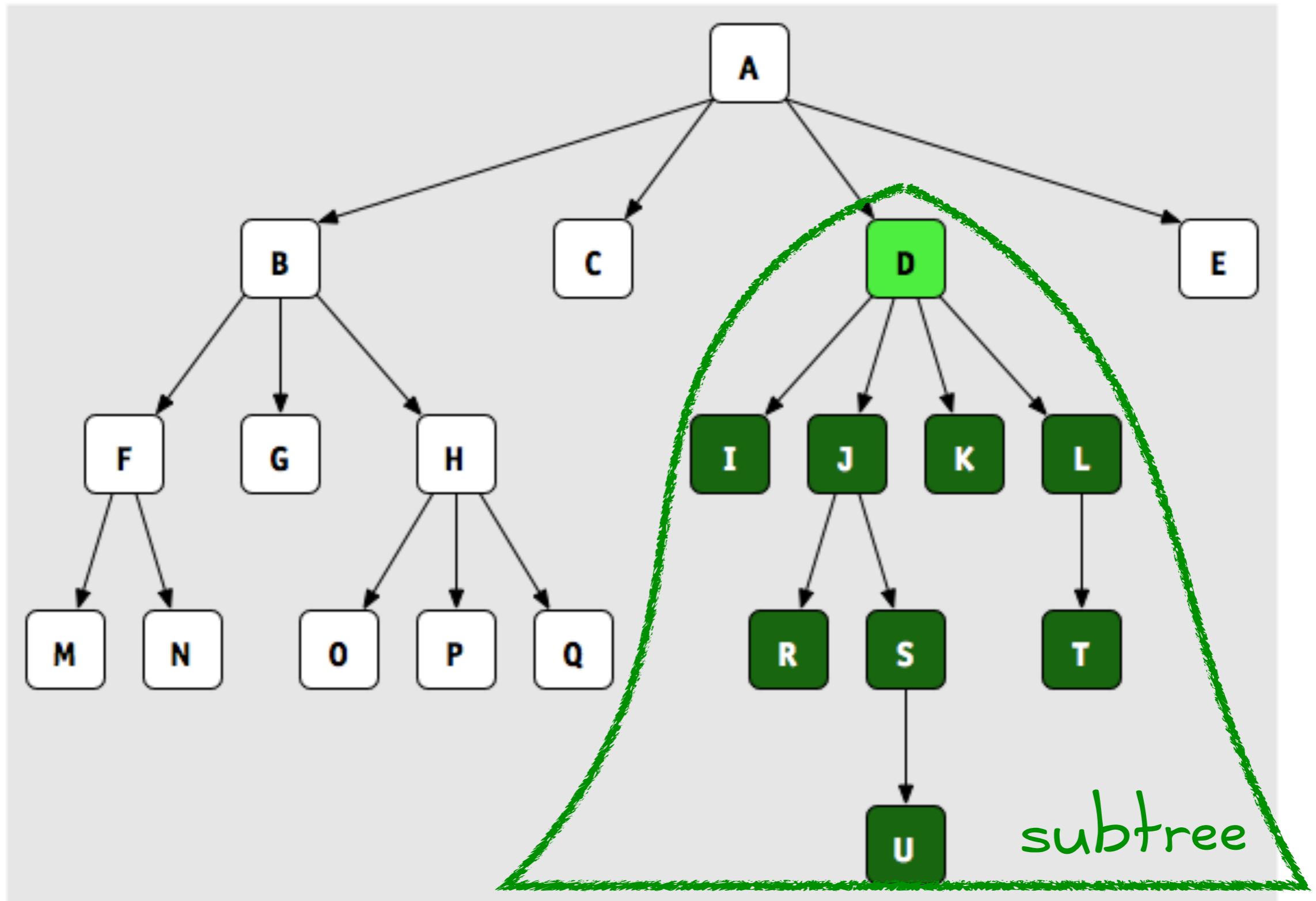
Which of these are (not) trees? (And why?)



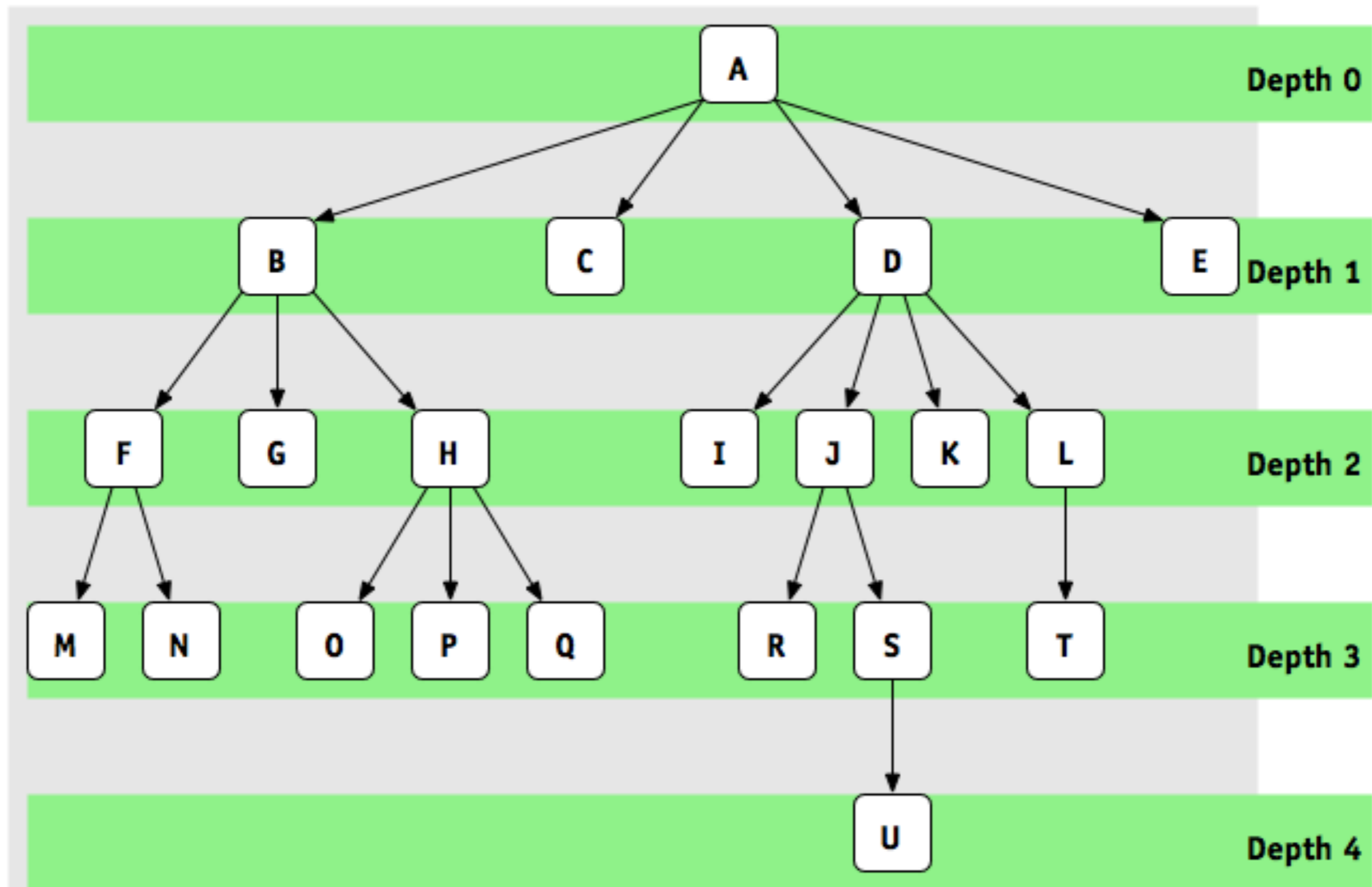
Ancestors



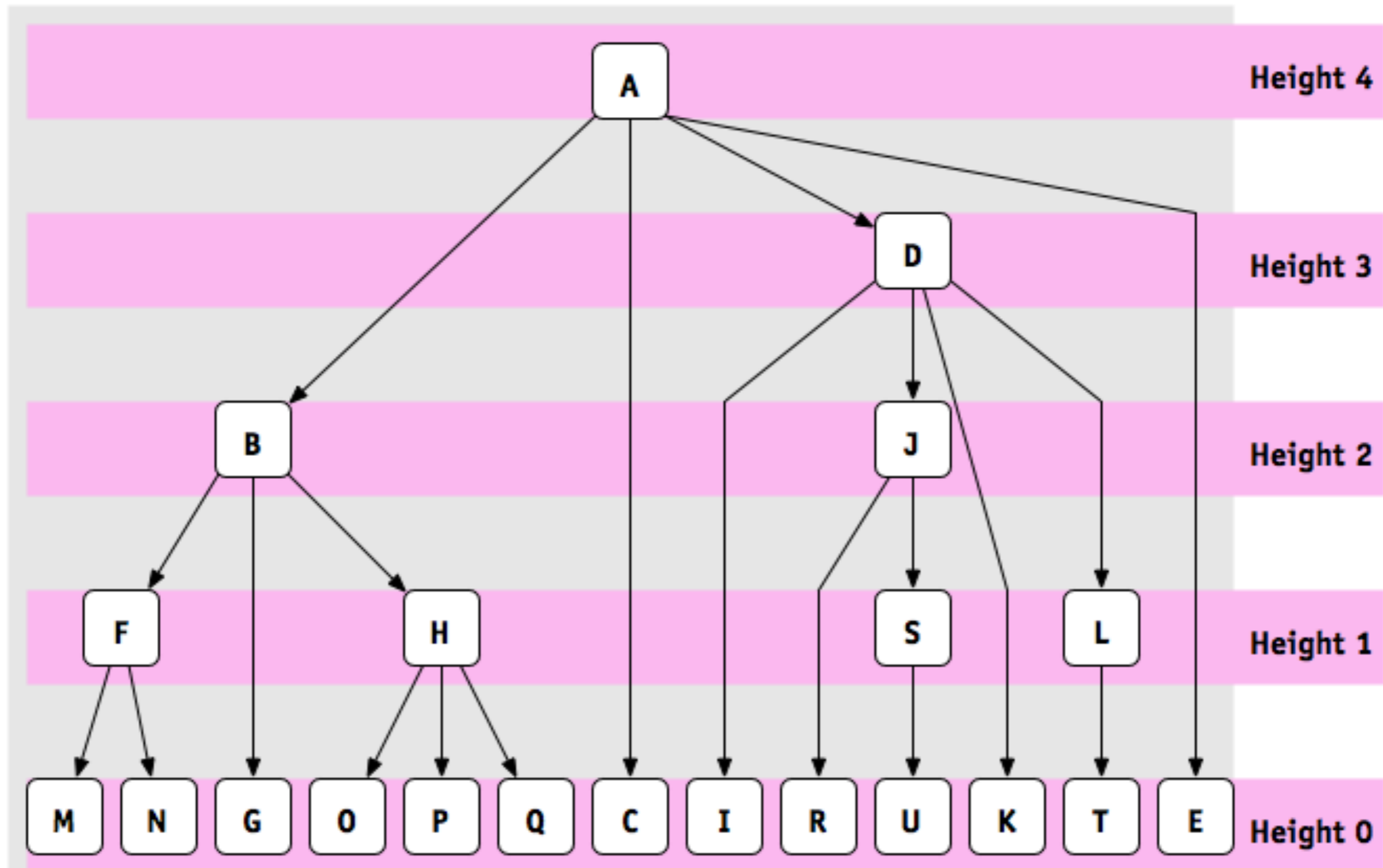
Descendants



Depth



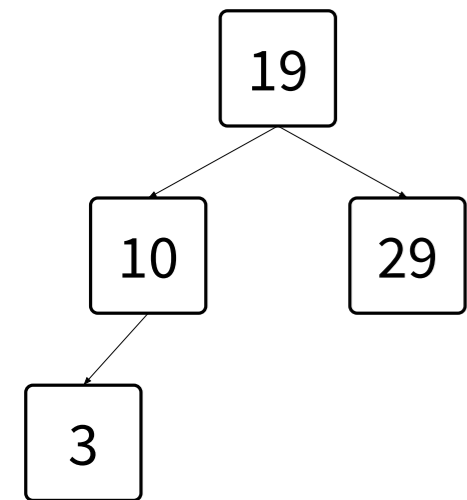
Height



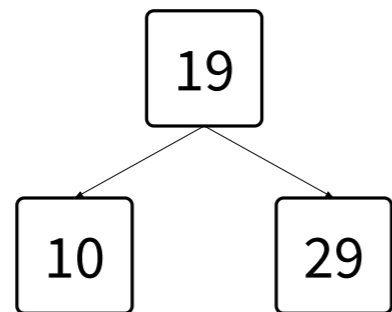
Tree height

the length of the longest path from the root to a leaf

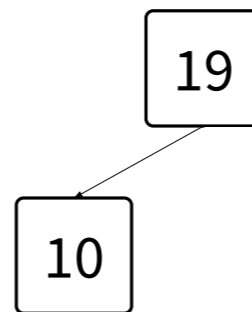
$h = 2$



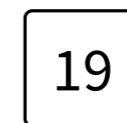
$h = 1$



$h = 1$



$h = 0$

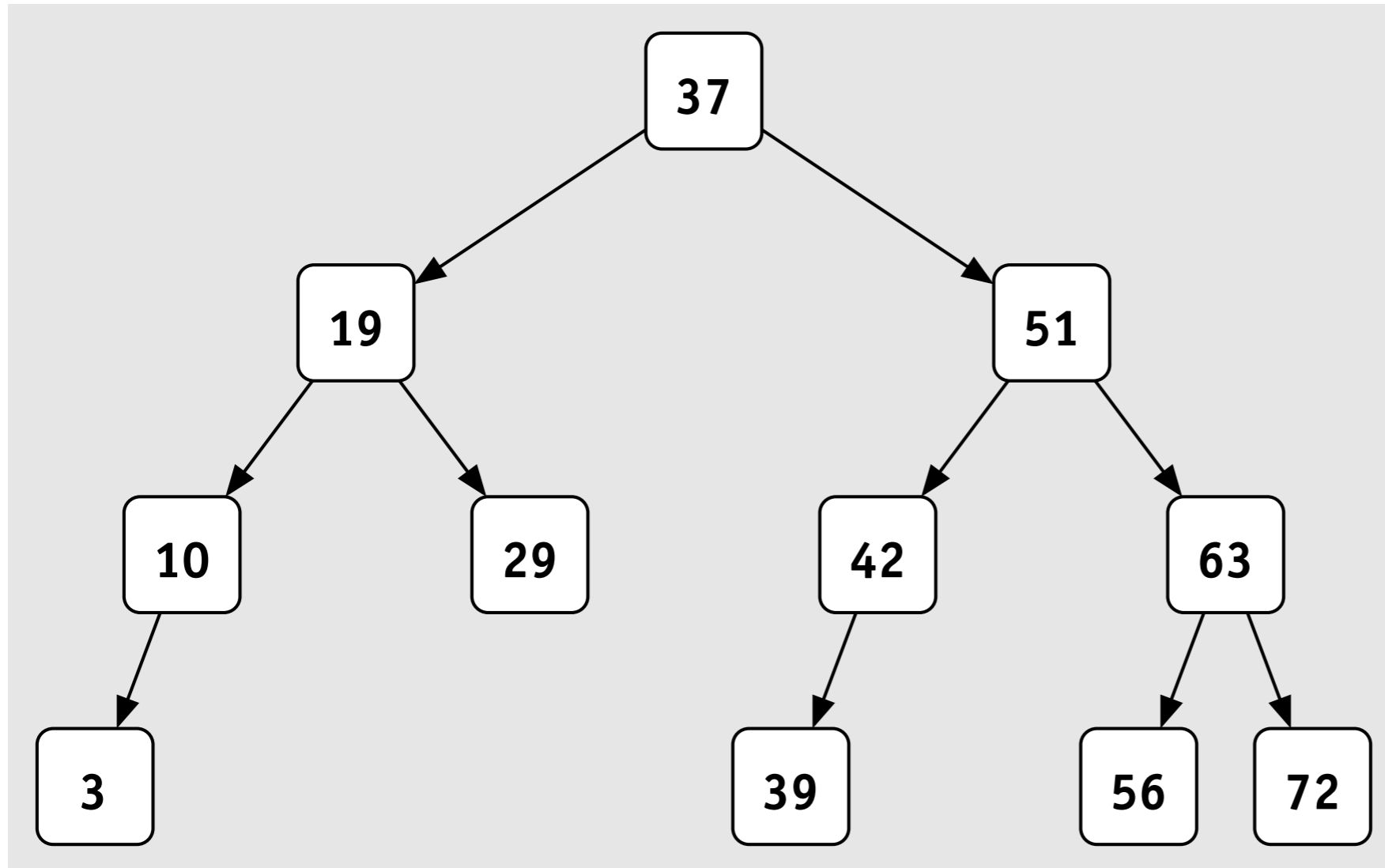


$h = -1 (!)$

The height of an empty tree is -1.

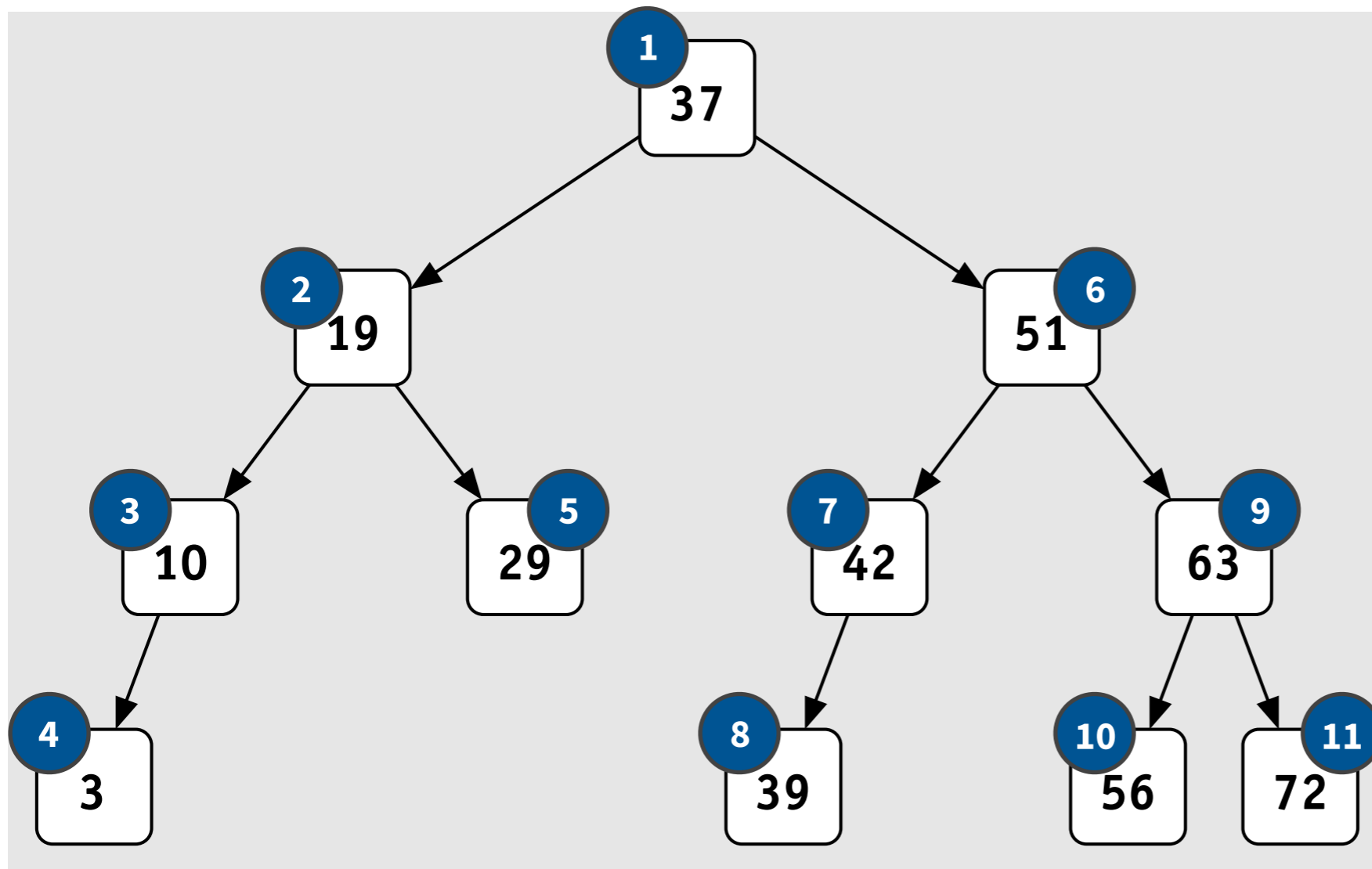
Binary trees

structure constraint: every node has at most two children



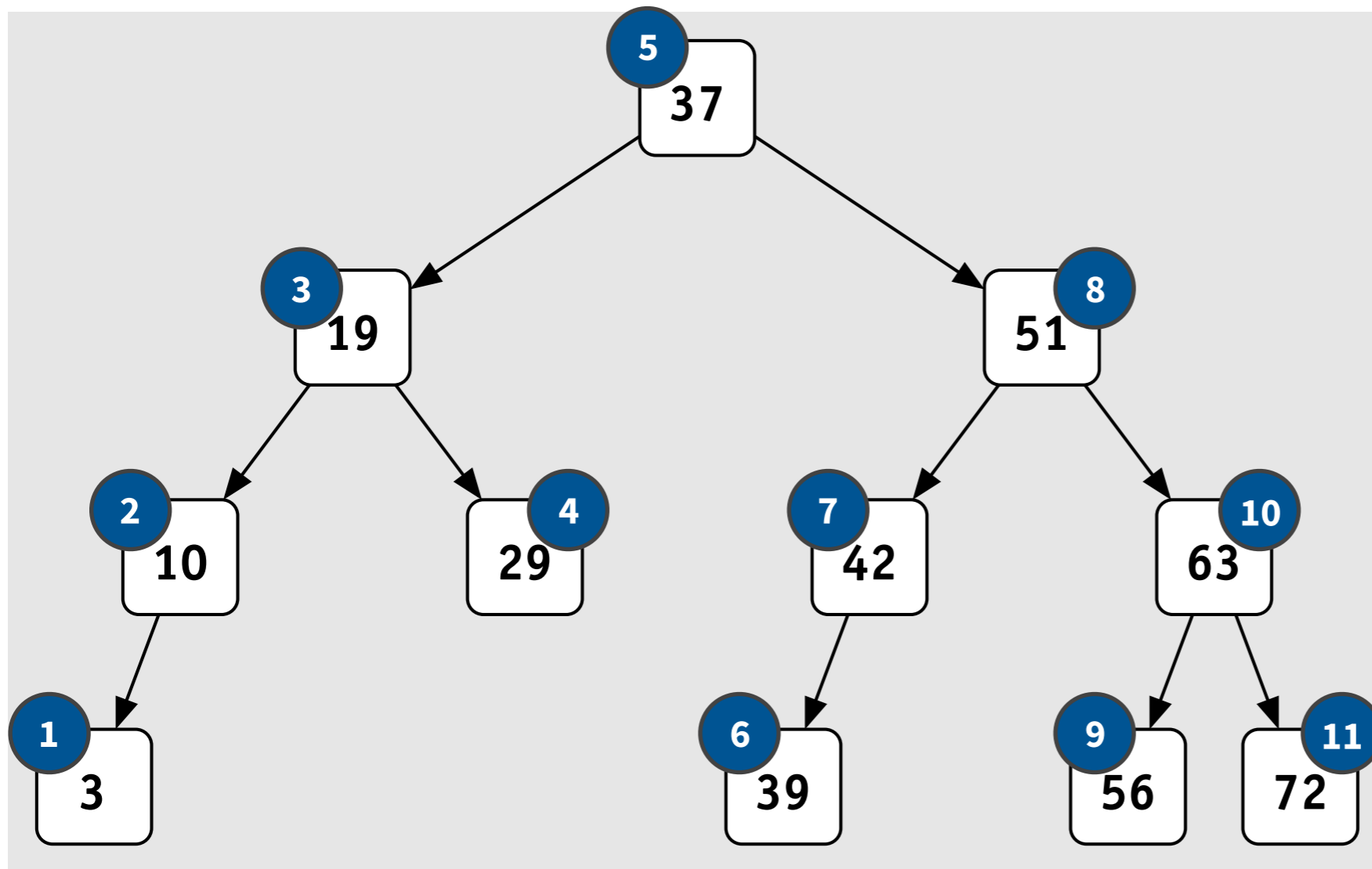
Preorder traversal

Visit the root, then preorder traverse the left subtree, then preorder traverse the right subtree



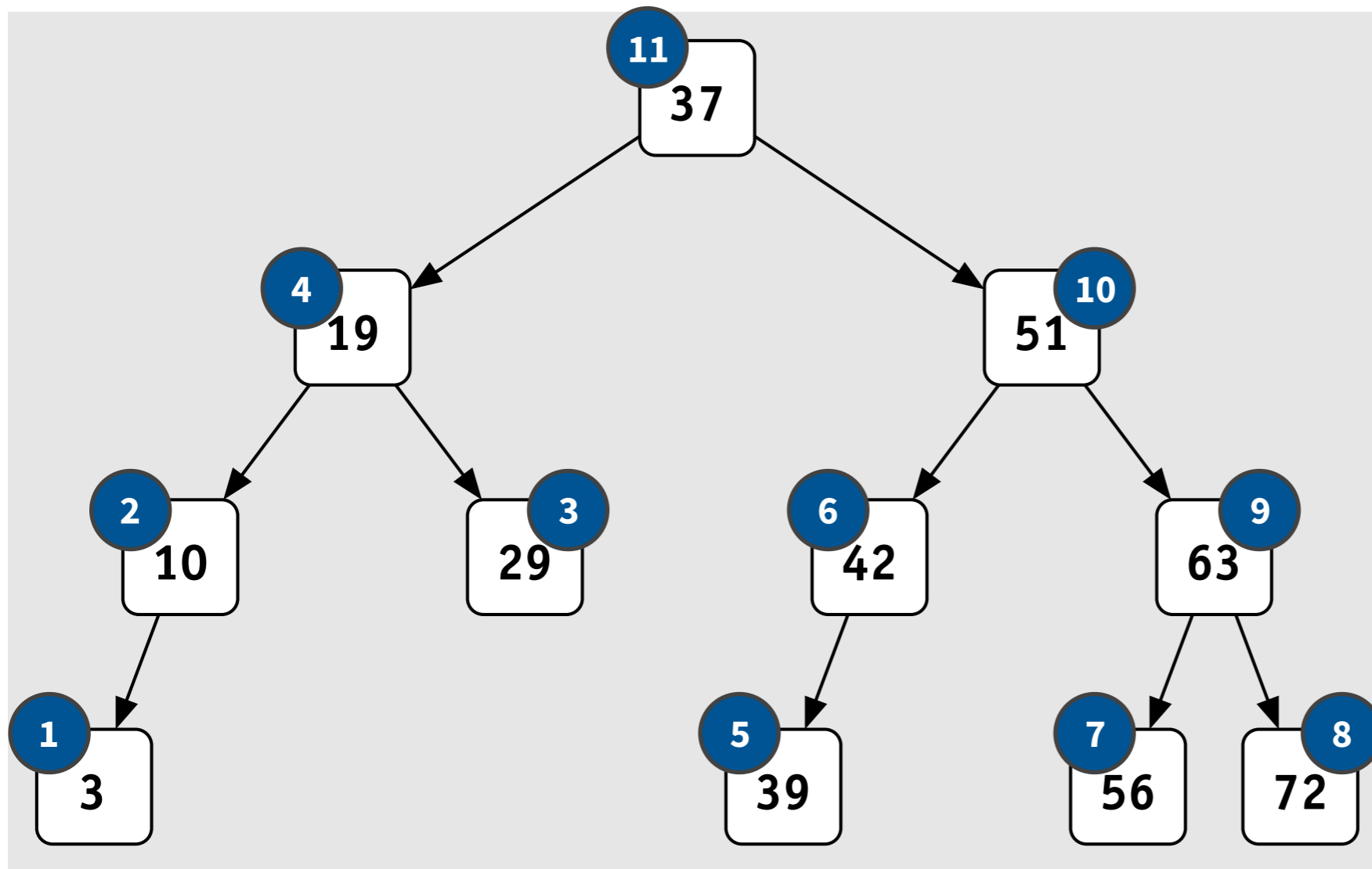
Inorder traversal

Inorder traverse the left subtree, then visit the root, then inorder traverse the right subtree



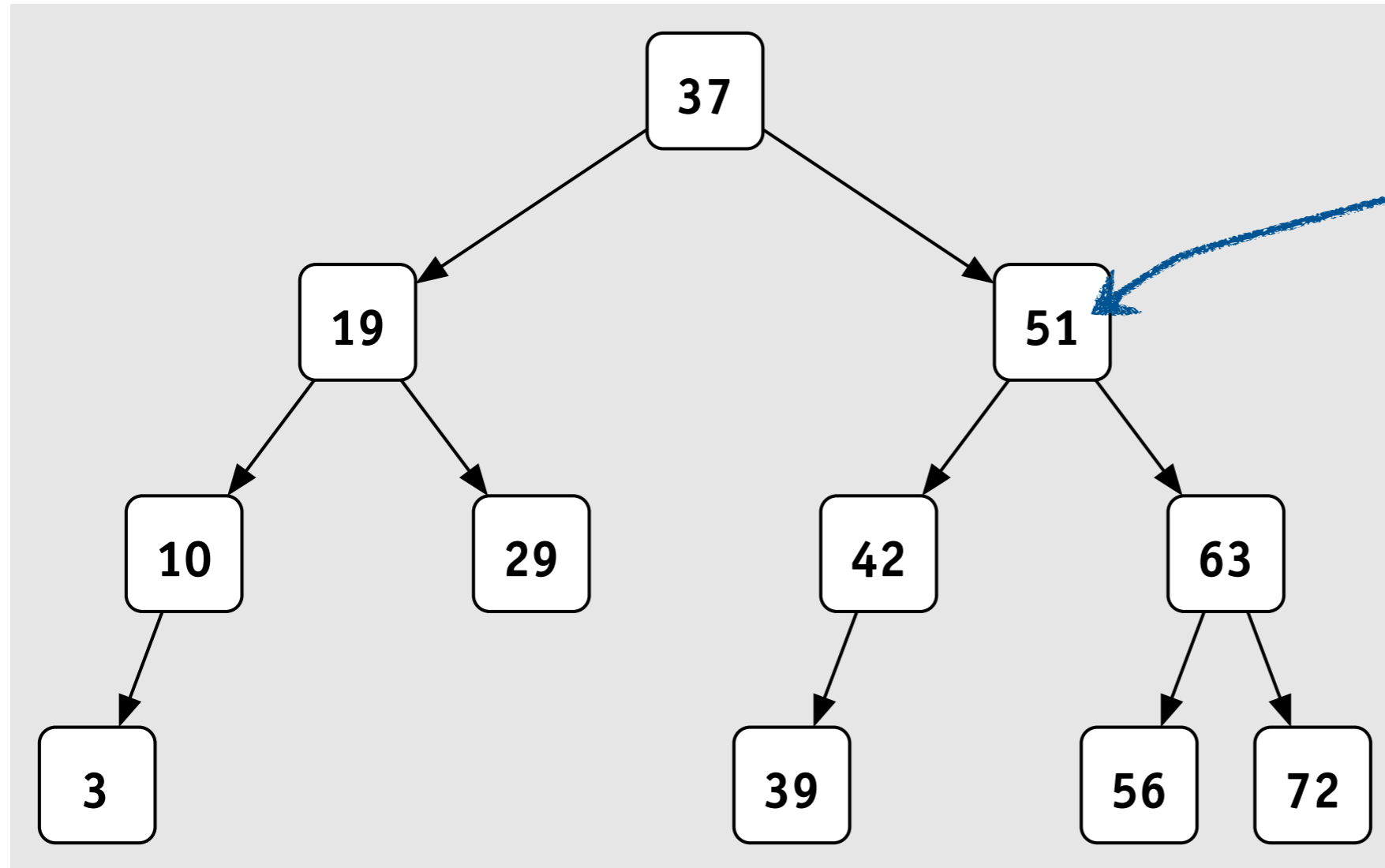
Postorder traversal

Postorder traverse the left subtree, then postorder traverse the right subtree, then visit the root



Binary *search* trees (BSTs)

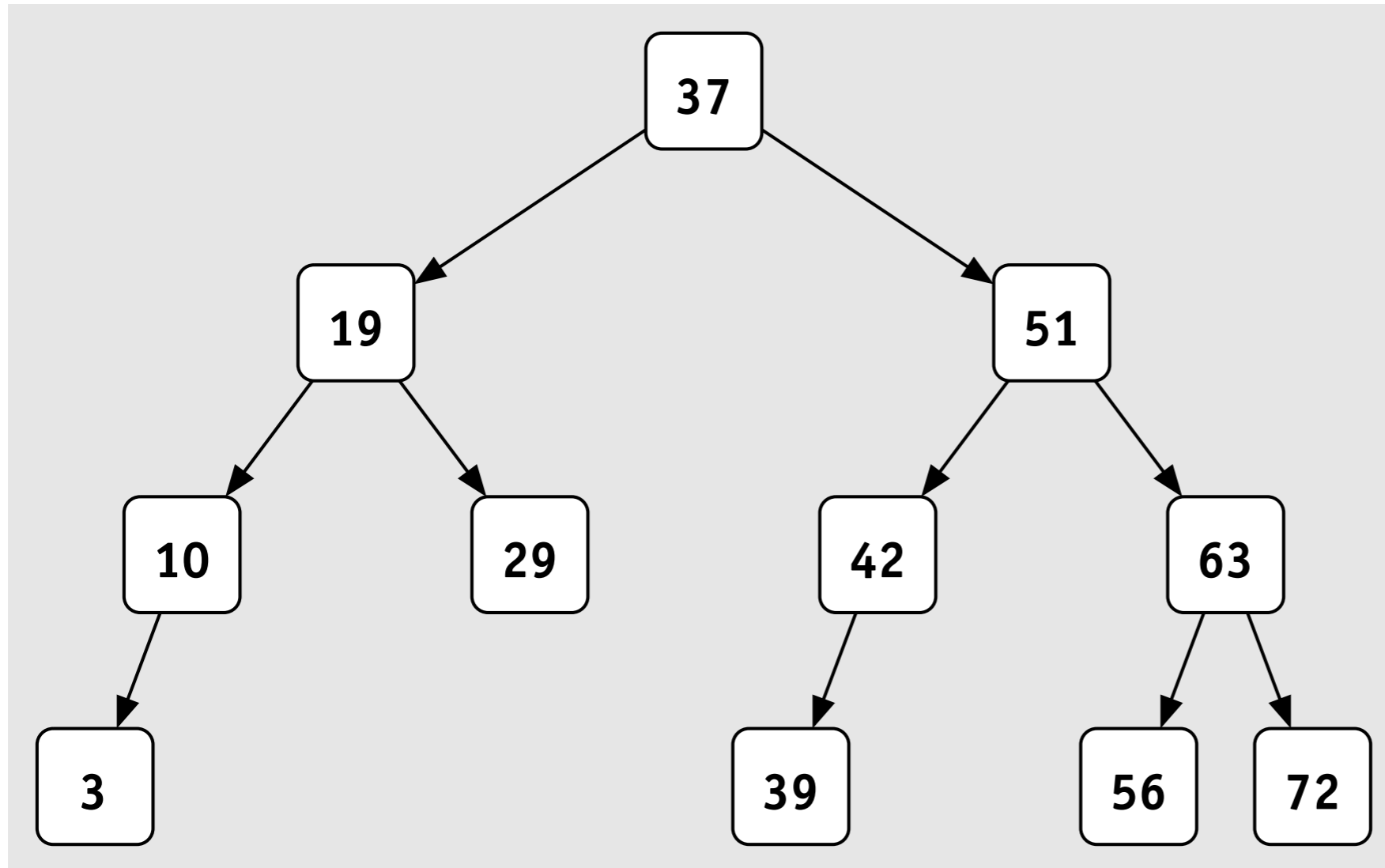
order constraint: every parent is greater than all the nodes in its left subtree and less than all the nodes in the right



(unique) key
the value used for search

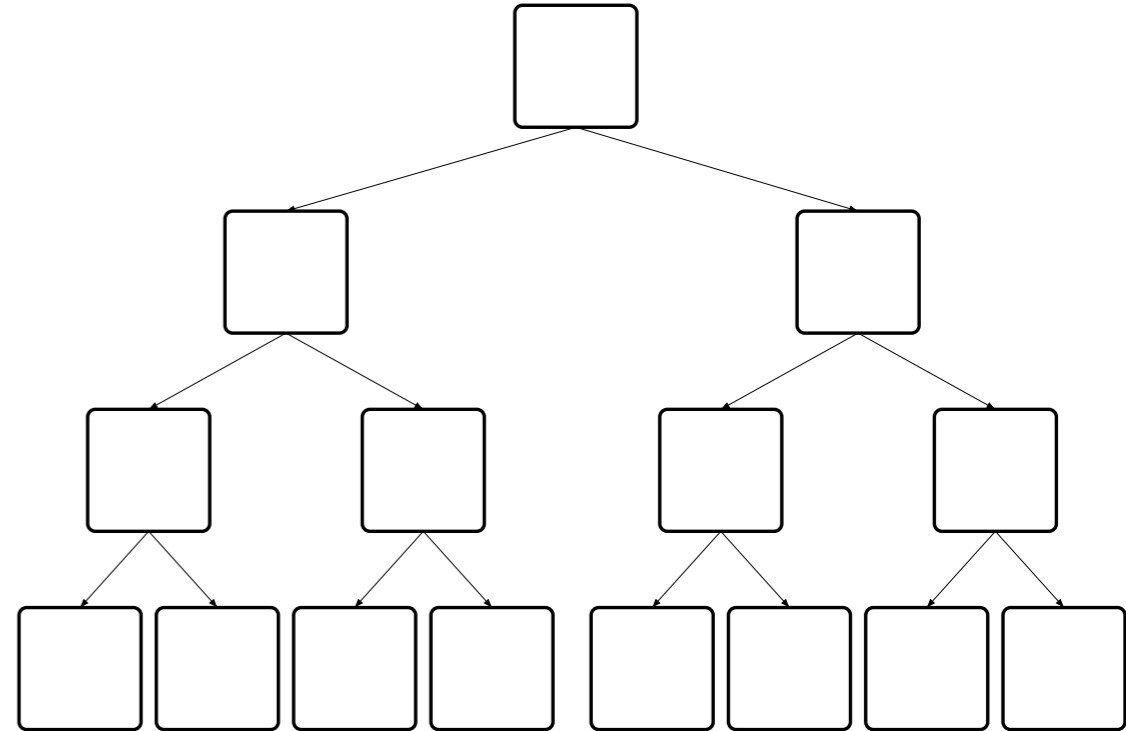
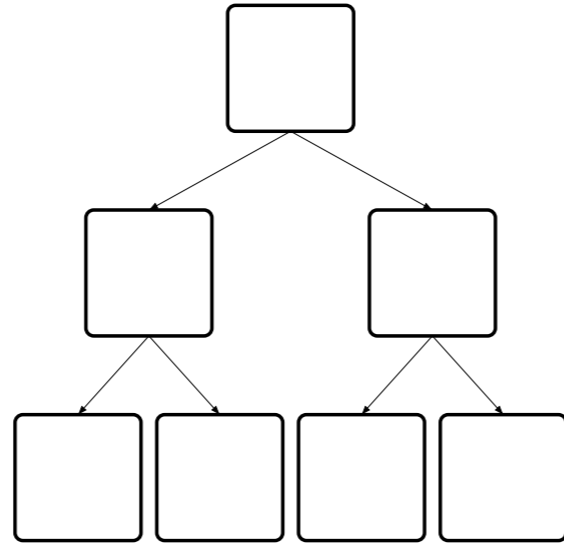
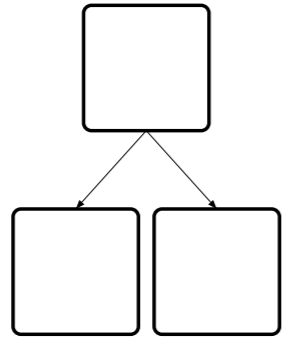
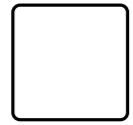
Balanced binary search trees

structure constraint: every subtree is about the same size as its sibling



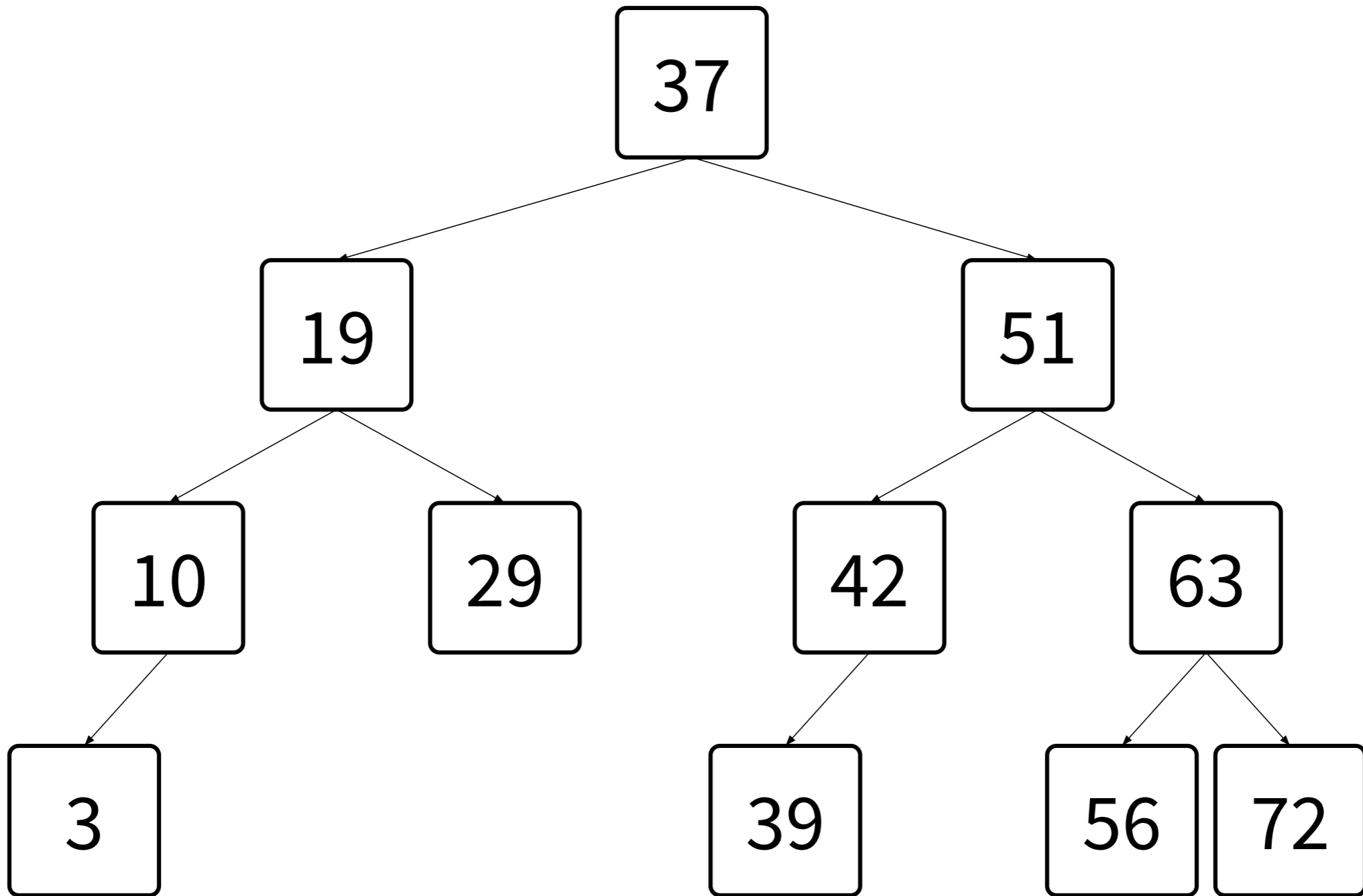
Perfect trees

structure: all leaves are at the same level and every level is full



- Most trees aren't perfect (why not?)
- But perfect trees are useful for analyzing balanced trees.

BST algorithm: find



BST algorithm: find

Given a BST *values* and a number *i*:

find(*i*, *values*):

If the tree is empty, return false.

Let *key* be the value at the root of the tree.

If *key* is *i*, return true.

If $i < \text{key}$, call find on the left subtree.

If $i > \text{key}$, call find on the right subtree.

BST algorithm: insert

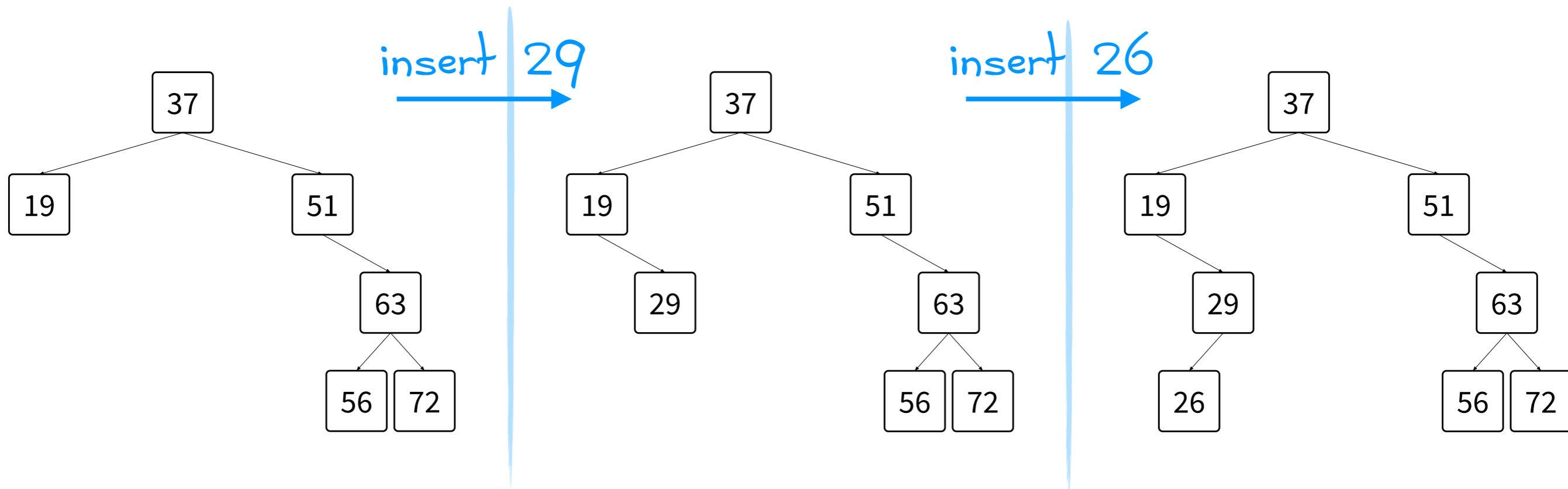
we'll assume that i
is not in the tree

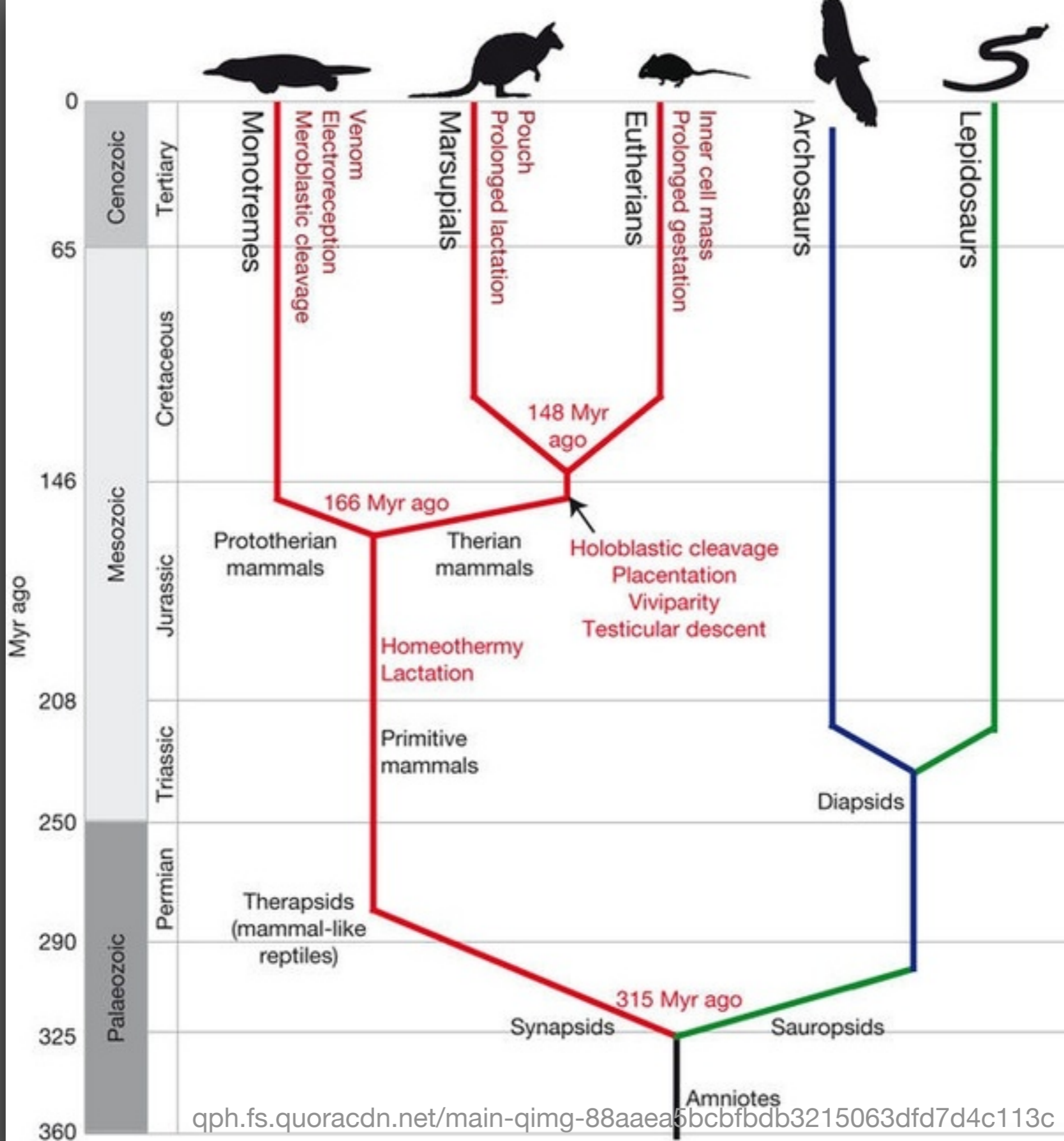
Given a BST *values* and a number i :

insert(i , values):

Look for i in values.

Insert i as a leaf where it should be.





Designing and implementing a new data structure

Interface and implementation

- Interface

Answers: **what** can this data structure do

- Implementation: encoding

Answers: **how** the structure is stored, using existing data structures

- Implementation: operations

Answers: **how** the structure provides its interface via algorithms over the encoding

It should be possible to replace the implementation without modifying the interface.

We'll talk only about the interface for trees
(but you have access to the code for the implementation).

Our Racket trees: Interface

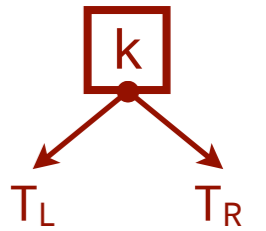
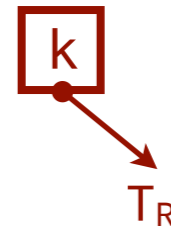
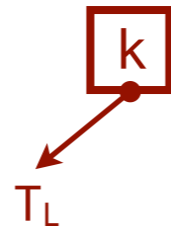
Inductive data structure, manipulated via constructors, accessors, and operations

constructors <i>put together</i>	accessors <i>take apart</i>	operations <i>often recursive</i>
<code>empty-tree</code>	<code>(empty-tree? <tree>)</code>	<code>(size <tree>)</code>
	<code>(leaf? <tree>)</code>	<code>(height <tree>)</code>
<code>(make-leaf <key>)</code>	<code>(root <tree>)</code>	<code>(find <value> <tree>)</code>
	<code>(left <tree>)</code>	<code>(insert <value> <tree>)</code>
<code>(make-tree <key> <left> <right>)</code>	<code>(right <tree>)</code>	<code>(traverse-inorder <tree>)</code> <code>(traverse-preorder <tree>)</code> <code>(traverse-postorder <tree>)</code>

Our BSTs won't be balanced.

What are some good test cases for trees?

ϵ



size

Firstname Lastname

Th. 10 / 18

; the number of nodes in the tree
(define (size tree))

(Your response)

size

Firstname Lastname

Th. 10 / 18

; the number of nodes in the tree

```
(define (size tree)
  (if (empty-tree? tree)
    0
    (+ 1
      (size (left tree))
      (size (right tree)))))
```


Worst-case analysis

How bad can it get?

Given a collection of size N and an operation:

What's the worst input for the operation?

How expensive is the operation, for that input? (cost = # of elements visited)

	find	insert	min
List			
Tree			
Binary search tree (BST)			

For trees (including unbalanced BSTs), the worst-case version of an N -element tree is a “stick” (i.e., a linked list).

Worst-case analysis

How bad can it get?

Given a collection of size N and an operation:

What's the worst input for the operation?

How expensive is the operation, for that input? (cost = # of elements visited)

	find	insert	min	list elements in order
List	$O(n)$ elements visited	$O(1)$ elements visited	$O(n)$ elements visited	$O(n \log n)$ elements visited
Tree	$O(n)$ elements visited	$O(1)$ elements visited	$O(n)$ elements visited	$O(n \log n)$ elements visited
Binary search tree (BST)	$O(n)$ elements visited	$O(n)$ elements visited	$O(n)$ elements visited	$O(n)$ elements visited
<i>balanced</i> Binary search tree (BST)	$O(\log n)$ elements visited	$O(\log n)$ elements visited	$O(\log n)$ elements visited	$O(n)$ elements visited

For trees (including unbalanced BSTs), the worst-case version of an N -element tree is a “stick” (i.e., a linked list).

Analyze size, using a recurrence relation

For a given cost metric: **additions**; on the worst-case input: **a stick**

1. Translate the base case(s), using specific **input sizes**

How many steps does this base case take?

2. Translate the recursive case(s), using **input size N**

Define $T(N)$ recursively, in terms of smaller cost.

```
(define (size tree)
```

```
  (if (empty-tree? tree)
```

```
      0
```

```
      (+ 1 (size (left tree)) (size (right tree))))
```

$$T(0) = 0$$

$$T(N) = 1 + T(N-1) + 0$$

$$T(N) = 1 + T(N-1) + 0$$

$$= 1 + 1 + T(N-2)$$

$$= 1 + 1 + 1 + T(N-3)$$

...

$$= 1 + 1 + 1 + \dots 1 + T(N-N)$$

$$= 1 * 1 + T(N-1)$$

$$= 2 * 1 + T(N-2)$$

$$= 3 * 1 + T(N-3)$$

...

$$= N * 1 + T(N-N) = N \in O(N)$$